

ECE595 / STAT598: Machine Learning I

Lecture 19.1: Support Vector Machine - Concept of Margin

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Outline

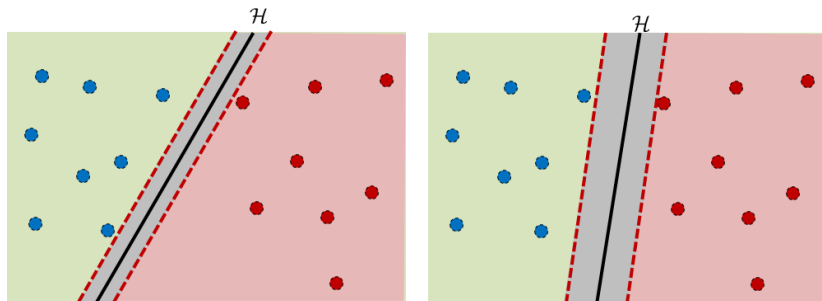
Support Vector Machine

- Lecture 19 SVM 1: The Concept of Max-Margin
- Lecture 20 SVM 2: Dual SVM
- Lecture 21 SVM 3: Kernel SVM

This lecture: Support Vector Machine 1

- Concept of Margin
 - Distance from point to plane
 - Margin
 - Max Margin Classifier
- SVM
 - SVM via Optimization
 - Programming SVM
 - Visualization

Margin and Max-Margin Classifier



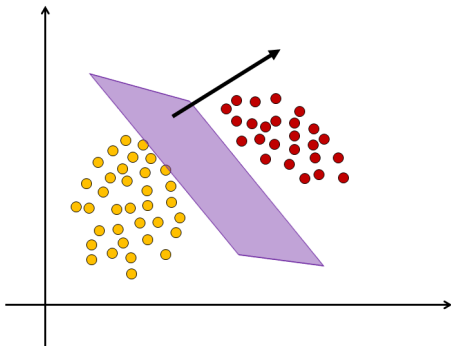
- **Margin:** Smallest gap between the two classes
- **Max-Margin Classifier:** A classifier that maximizes the margin
- **What do we need?**
 - How to measure the distance from a point to a plane?
 - How to formulate a max margin problem?
 - How to solve the max margin problem?

Recall: Linear Discriminant Function

- In high-dimension,

$$g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + w_0.$$

is a hyperplane.

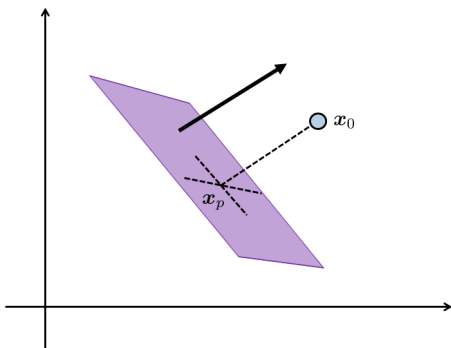


- **Separating Hyperplane:**

$$\begin{aligned} \mathcal{H} &= \{\mathbf{x} \mid g(\mathbf{x}) = 0\} \\ &= \{\mathbf{x} \mid \mathbf{w}^T \mathbf{x} + w_0 = 0\} \end{aligned}$$

- $\mathbf{x} \in \mathcal{H}$ means \mathbf{x} is on the decision boundary.
- $\mathbf{w} / \|\mathbf{w}\|_2$ is the **normal vector** of \mathcal{H} .

Recall: Distance from \mathbf{x}_0 to $g(\mathbf{x}) = 0$



Therefore, we can show that

$$\begin{aligned}g(\mathbf{x}_0) &= \mathbf{w}^T \mathbf{x}_0 + w_0 \\ &= \mathbf{w}^T \left(\mathbf{x}_p + \eta \frac{\mathbf{w}}{\|\mathbf{w}\|_2} \right) + w_0 \\ &= g(\mathbf{x}_p) + \eta \|\mathbf{w}\|_2 = \eta \|\mathbf{w}\|_2.\end{aligned}$$

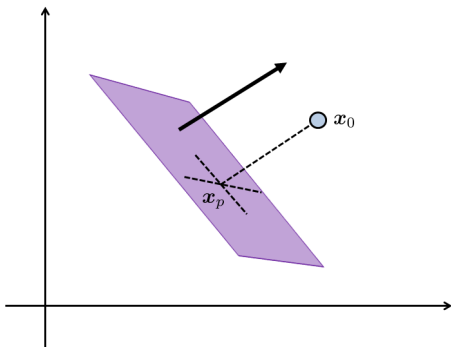
- Pick a point \mathbf{x}_p on \mathcal{H}
- \mathbf{x}_p is the closest point to \mathbf{x}_0
- $\mathbf{x}_0 - \mathbf{x}_p$ is the normal direction
- So, for some scalar $\eta > 0$,

$$\mathbf{x}_0 - \mathbf{x}_p = \eta \frac{\mathbf{w}}{\|\mathbf{w}\|_2}$$

- \mathbf{x}_p is on \mathcal{H} . So

$$g(\mathbf{x}_p) = \mathbf{w}^T \mathbf{x}_p + w_0 = 0$$

Recall: Distance from x_0 to $g(x) = 0$



- So distance is

$$\eta = \frac{g(x_0)}{\|w\|_2}$$

- The closest point x_p is

$$\begin{aligned}x_p &= x_0 - \eta \frac{w}{\|w\|_2} \\ &= x_0 - \frac{g(x_0)}{\|w\|_2} \cdot \frac{w}{\|w\|_2}.\end{aligned}$$

Conclusion:

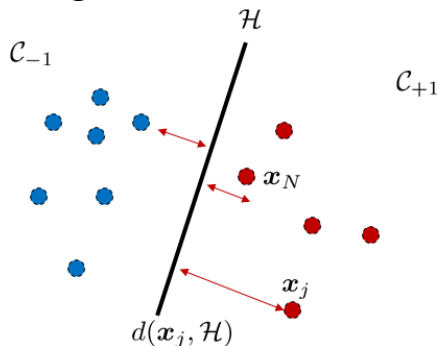
$$x_p = x_0 - \underbrace{\frac{g(x_0)}{\|w\|_2}}_{\text{distance}} \cdot \underbrace{\frac{w}{\|w\|_2}}_{\text{normal vector}}$$

Unsigned Distance

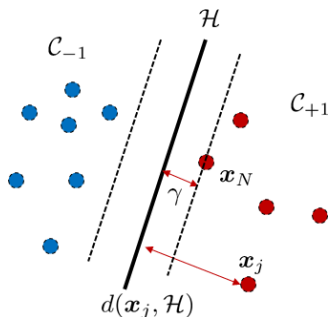
- We define the distance between a data point \mathbf{x}_j and a separating hyperplane as

$$d(\mathbf{x}_j, \mathcal{H}) = \frac{|g(\mathbf{x}_j)|}{\|\mathbf{w}\|_2} = \frac{|\mathbf{w}^T \mathbf{x}_j + w_0|}{\|\mathbf{w}\|_2}.$$

- $d(\mathbf{x}_j, \mathcal{H})$ is called **unsigned** distance



Margin

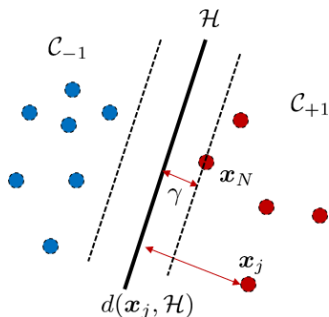


- Among all the unsigned distances, pick the smallest one.
- Margin: γ such that

$$\gamma = \min_{j=1, \dots, N} d(\mathbf{x}_j, \mathcal{H}).$$

- Without loss of generality, assume \mathbf{x}_N is the closest point.

More about Margin



- Margin: γ such that

$$\gamma = \min_{j=1, \dots, N} d(\mathbf{x}_j, \mathcal{H}).$$

- γ depends on (\mathbf{w}, w_0) .
- γ always exist because training set is finite.
- $\gamma \geq 0$, and is zero when \mathbf{x}_N is on the boundary.

Signed Distance

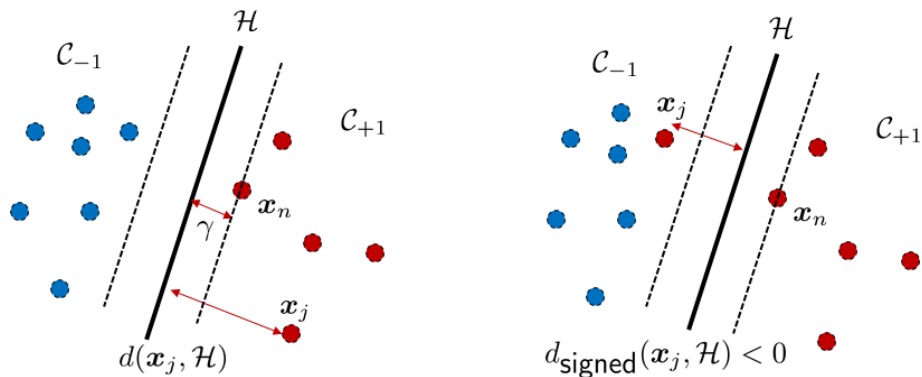
- $d(\mathbf{x}_j, \mathcal{H})$ is unsigned
- So γ does not tell whether a point \mathbf{x}_j is correctly classified or not
- Assume that the labels are defined as $y_j \in \{-1, +1\}$
- Then define a **signed distance**

$$\begin{aligned}d_{\text{signed}}(\mathbf{x}_j, \mathcal{H}) &= y_j \left(\frac{\mathbf{w}^T \mathbf{x}_j + w_0}{\|\mathbf{w}\|_2} \right) \\ &= \begin{cases} \geq 0, & \text{correctly classify } \mathbf{x}_j \\ < 0, & \text{incorrectly classify } \mathbf{x}_j. \end{cases}\end{aligned}$$

- Recall perceptron loss:

$$\mathcal{L}(\mathbf{x}_j) = \max \left\{ -y_j(\mathbf{w}^T \mathbf{x}_j + w_0), 0 \right\}$$

Unsigned VS Signed Distance



- Unsigned distance: Just the distance
- Signed distance: Distance plus whether on the correct side

Max-Margin Objective

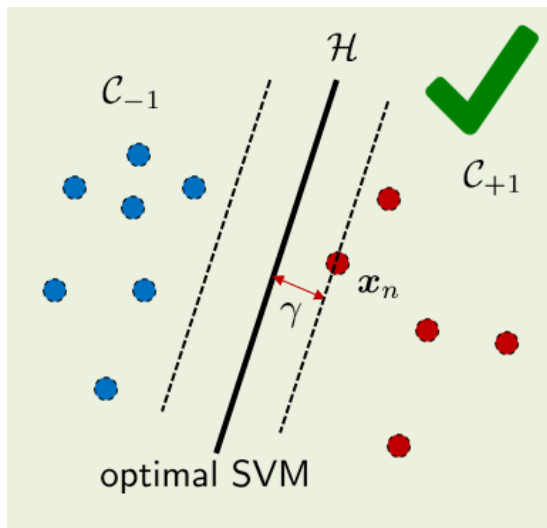
- **Assumptions:** Linearly separable.
- This means

$$y_j \left(\frac{\mathbf{w}^T \mathbf{x}_j + w_0}{\|\mathbf{w}\|_2} \right) \geq \gamma, \quad j = 1, \dots, N.$$

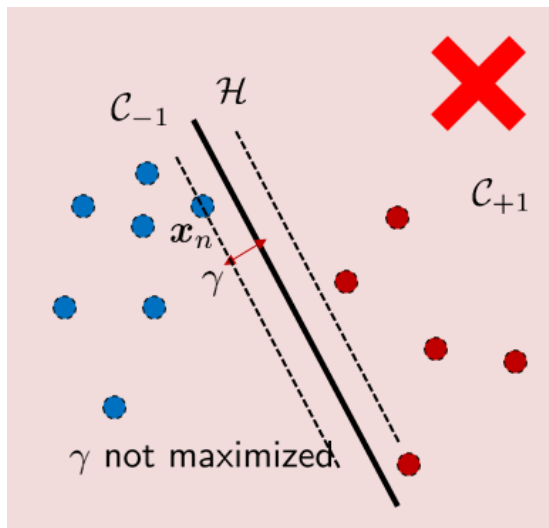
- All training samples are correctly classified.
- All training samples are at least γ from the boundary.
- So the max-margin classifier is

$$\begin{aligned} & \underset{\mathbf{w}, w_0}{\text{maximize}} \quad \gamma \\ & \text{subject to} \quad y_j \left(\frac{\mathbf{w}^T \mathbf{x}_j + w_0}{\|\mathbf{w}\|_2} \right) \geq \gamma, \quad j = 1, \dots, N. \end{aligned}$$

Good or Bad?



Good or Bad?



Good or Bad?

