

ECE595 / STAT598: Machine Learning I

Lecture 24.2: Probably Approximately Correct - PAC Framework

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Outline

- Lecture 22 Is Learning Feasible?
- Lecture 23 Probability Inequality
- **Lecture 24 Probably Approximate Correct**

Today's Lecture:

- Two ingredients of generalization
 - Training and testing error
 - Hoeffding inequality
 - Interpreting the bound
- **PAC Framework**
 - **PAC learnable**
 - **Confidence and accuracy**
 - **Example**

Accuracy and Confidence

Recall the equation

$$\mathbb{P}[|E_{\text{in}}(h) - E_{\text{out}}(h)| > \epsilon] \leq 2e^{-2\epsilon^2 N}$$

- $\delta = 2e^{-2\epsilon^2 N}$. **confidence:** $1 - \delta$.
- $\epsilon = \sqrt{\frac{1}{2N} \log \frac{2}{\delta}}$. **accuracy:** $1 - \epsilon$.
- Then the equation becomes

$$\mathbb{P}[|E_{\text{in}}(h) - E_{\text{out}}(h)| > \epsilon] \leq \delta$$

- which is equivalent to

$$\mathbb{P}[|E_{\text{in}}(h) - E_{\text{out}}(h)| \leq \epsilon] > 1 - \delta$$

Probably Approximately Correct

- **Probably:** Quantify error using probability:

$$\mathbb{P}[|E_{\text{in}}(h) - E_{\text{out}}(h)| \leq \epsilon] \geq 1 - \delta$$

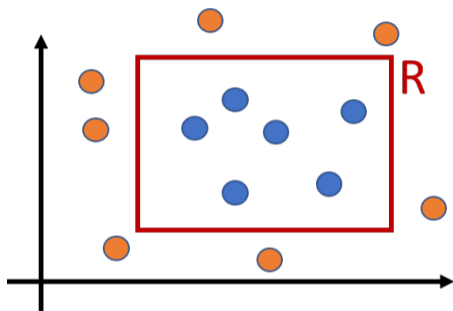
- **Approximately Correct:** In-sample error is an approximation of the out-sample error:

$$\mathbb{P}[|E_{\text{in}}(h) - E_{\text{out}}(h)| \leq \epsilon] \geq 1 - \delta$$

- If you can find an algorithm \mathcal{A} such that for any ϵ and δ , there exists an N which can make the above inequality holds, then we say that the target function is **PAC-learnable**.
- The following example is taken from Mohri et al. Foundation of Machine Learning, Example 2.4.

Example: Rectangle Classifier

Consider a set of 2D data points.



- The target function is a rectangle R
- Inside R : blue. Outside R : orange. Data is intrinsically separable.
- Goal: Pick a hypothesis rectangle R' using the available data point
- Question: Is this problem PAC learnable?

What Shall We Do?

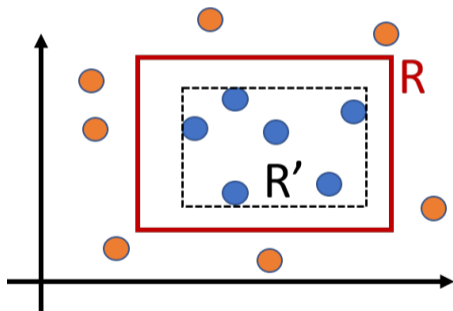
- This question is very general.
- It asks about the nature of the problem.
- We want to show that this problem is indeed PAC learnable.
- To do so, we need to propose an **algorithm** \mathcal{A} which takes the training data and returns an R' , such that for any $\epsilon > 0$ and $\delta > 0$, there exists an N (which is a function of ϵ and δ) with

$$\mathbb{P}[|E_{\text{in}}(R') - E_{\text{out}}(R')| > \epsilon] \leq \delta.$$

- If we find such algorithm, then the problem is PAC learnable.

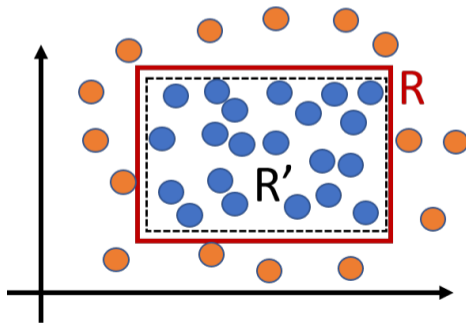
Proposed Algorithm

- \mathcal{A} : Give me the data point points, find the **tightest rectangle** that covers the blue circles.



Intuition

- As N grows, we can find a R' which is getting closer and closer to R .
- So for any $\epsilon > 0$ and $\delta > 0$, it seems possible that as long as N is large enough we will be able to make training error close to testing error.
- See Appendix for proof.



Summary

- Not all problems are learnable.
- Those that are learnable require **training and testing** samples are correlated.
- Then **Hoeffding inequality** applies

$$\mathbb{P}[|E_{\text{out}}(R') - E_{\text{in}}(R')| > \epsilon] \leq \delta.$$

- For any accuracy ϵ and any confidence δ , if you can find an algorithm \mathcal{A} such that as long as N is large enough the above inequality can be proved, then the target function is PAC learnable.
- Next time: Look at the hypothesis set \mathcal{H} .

Reading List

- Yasar Abu-Mustafa, Learning from Data, Chapter 1.3, 2.1.
- Mehryar Mohri, Foundations of Machine Learning, Chapter 2.1.
- Martin Wainwright, High Dimensional Statistics, Cambridge University Press 2019. (Chapter 2)
- CMU Note <https://www.cs.cmu.edu/~mgormley/courses/10601-s17/slides/lecture28-pac.pdf>
- Iowa State Note <http://web.cs.iastate.edu/~honavar/pac.pdf>
- Princeton Note https://www.cs.princeton.edu/courses/archive/spring08/cos511/scribe_notes/0211.pdf
- Stanford Note <http://cs229.stanford.edu/notes/cs229-notes4.pdf>