

# ECE595 / STAT598: Machine Learning I

## Lecture 25.1: Generalization Bound - $M$ Hypothesis

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# Outline

- Lecture 25 Generalization
- Lecture 26 Growth Function
- Lecture 27 VC Dimension

## Today's Lecture:

- $M$  Hypothesis
  - PAC framework
  - Guarantee and Possibility
  - The  $M$  factor
- Generalization Bound
  - $\mathcal{H}$
  - $f$
  - Lower and upper limits
- Handling  $M$  hypothesis
  - A preview

# Probably Approximately Correct

- **Probably:** Quantify error using probability:

$$\mathbb{P}[|E_{\text{in}}(h) - E_{\text{out}}(h)| \leq \epsilon] \geq 1 - \delta$$

- **Approximately Correct:** In-sample error is an approximation of the out-sample error:

$$\mathbb{P}[|E_{\text{in}}(h) - E_{\text{out}}(h)| \leq \epsilon] \geq 1 - \delta$$

- If you can find an algorithm  $\mathcal{A}$  such that for any  $\epsilon$  and  $\delta$ , there exists an  $N$  which can make the above inequality holds, then we say that the target function is **PAC-learnable**.

## Guarantee VS Possibility

Difference between deterministic and probabilistic learning.

- **Deterministic:**
  - “Can  $\mathcal{D}$  tell us something *certain* about  $f$  outside  $\mathcal{D}$ ?”
  - The answer is NO.
  - Anything outside  $\mathcal{D}$  has uncertainty. There is no way to deal with this uncertainty.
- **Probabilistic:**
  - “Can  $\mathcal{D}$  tell us something *possibly* about  $f$  outside  $\mathcal{D}$ ?”
  - The answer is YES.
  - If training and testing have the same distribution  $p(\mathbf{x})$ , then training can say something about testing.
  - Assume all samples are independently drawn from  $p(\mathbf{x})$ .

## One Hypothesis versus the Final Hypothesis

- In this equation

$$\mathbb{P}[|E_{\text{in}}(h) - E_{\text{out}}(h)| > \epsilon] \leq 2e^{-2\epsilon^2 N},$$

the hypothesis  $h$  is *fixed*.

- This  $h$  is chosen **before** we look at the dataset.
- If  $h$  is chosen **after** we look at the dataset, then Hoeffding is invalid.
- We have to choose a  $h$  from  $\mathcal{H}$  during the learning process.
- The  $h$  we choose depends on  $\mathcal{D}$ .
- This  $h$  is the final hypothesis  $g$ .
- When you need to choose  $g$  from  $h_1, \dots, h_M$ , you need to repeat Hoeffding  $M$  times.

## The Factor “ $M$ ”

You can show that

$$\begin{aligned} |E_{\text{in}}(g) - E_{\text{out}}(g)| > \epsilon &\implies |E_{\text{in}}(h_1) - E_{\text{out}}(h_1)| > \epsilon \\ \text{or } |E_{\text{in}}(h_2) - E_{\text{out}}(h_2)| > \epsilon & \\ \dots & \\ \text{or } |E_{\text{in}}(h_M) - E_{\text{out}}(h_M)| > \epsilon. & \end{aligned}$$

- To have  $g$ , you need to consider  $h_1, \dots, h_M$
- You don't know which  $h_m$  to pick; So it is a “OR”
- So there is a sequence of “OR”

## The Factor “ $M$ ”

$$\begin{aligned} \mathbb{P}\left\{ |E_{\text{in}}(\mathbf{g}) - E_{\text{out}}(\mathbf{g})| > \epsilon \right\} &\stackrel{(a)}{\leq} \mathbb{P}\left\{ \begin{array}{l} |E_{\text{in}}(h_1) - E_{\text{out}}(h_1)| > \epsilon \\ \text{or } |E_{\text{in}}(h_2) - E_{\text{out}}(h_2)| > \epsilon \\ \dots \\ \text{or } |E_{\text{in}}(h_M) - E_{\text{out}}(h_M)| > \epsilon \end{array} \right\} \\ &\stackrel{(b)}{\leq} \sum_{m=1}^M \mathbb{P}\left\{ |E_{\text{in}}(h_m) - E_{\text{out}}(h_m)| > \epsilon \right\} \end{aligned}$$

- We need two identities
- (a) If-statement.  $\mathbb{P}[A] \leq \mathbb{P}[B]$  if  $A \Rightarrow B$
- (b) Union Bound.  $\mathbb{P}[A \text{ or } B] \leq \mathbb{P}[A] + \mathbb{P}[B]$

## The Factor “ $M$ ”

- Change this equation

$$\mathbb{P}\left\{ |E_{\text{in}}(h) - E_{\text{out}}(h)| > \epsilon \right\} \leq 2e^{-2\epsilon^2 N},$$

- to this equation

$$\mathbb{P}\left\{ |E_{\text{in}}(g) - E_{\text{out}}(g)| > \epsilon \right\} \leq 2Me^{-2\epsilon^2 N}.$$

- So what?  $M$  is a constant.
- Bad news:  $M$  can be large, or even  $\infty$ .
- A linear regression has  $M = \infty$ .
- Good news: It is possible to bound  $M$ .
- We will do it later. Let us look at the interpretation first.