

## Section 30 MOSFET Introduction

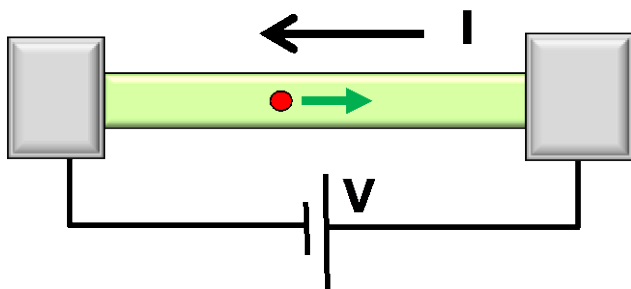
### 30.3 Velocity saturation in simplified theory

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Computer Engineering

# Section 30 MOSFET Introduction



$$I = G \times V$$
$$= q \times n \times v \times A$$

charge density    velocity    area

1

• 30.1 Sub-threshold (depletion) current

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• 30.2 Above-threshold, inversion current

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• 30.3 Velocity saturation in simplified theory

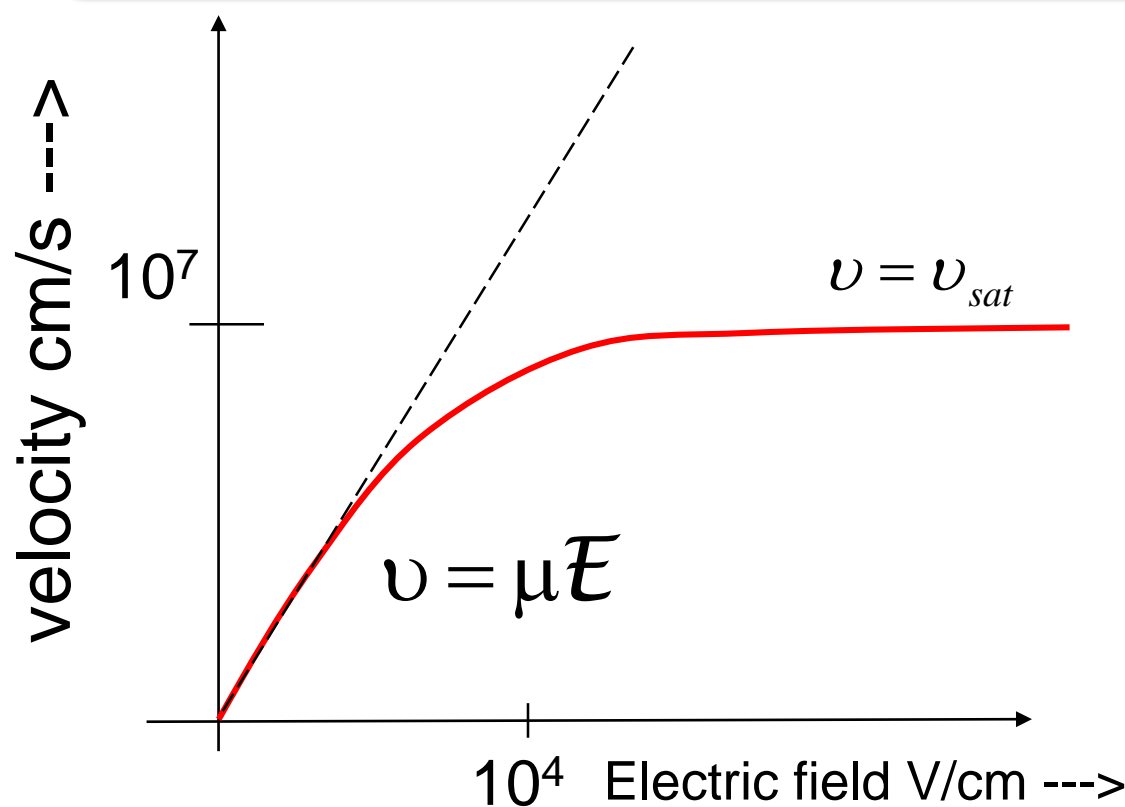
4

• 30.4 Comments on bulk charge theory & small transistors



# Velocity vs. Field Characteristic (electrons)

Velocity saturates at high fields because of scattering



$$v_d = \frac{-\mu E}{\left[1 + (E/E_c)^2\right]^{1/2}}$$

$$v_d = \frac{-\mu E}{1 + (|E|/E_c)}$$

$$v_{d,sat} = \mu E_c$$

This expression can be used to re-derive the expression for current since since mobility is now, in principle, a function of distance

$$\mu = \frac{\mu_0}{1 + \left(\frac{|E|}{E_c}\right)}$$

# Recap - derivation for MOSFET current

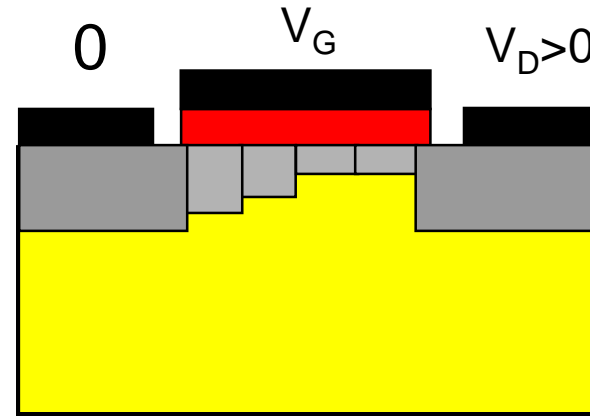
$$J_1 = Q_1 \mu_1 \mathcal{E}_1 = Q_1 \mu_1 \left. \frac{dV}{dy} \right|_1$$

$$J_2 = Q_2 \mu_2 \mathcal{E}_2 = Q_2 \mu_2 \left. \frac{dV}{dy} \right|_2$$

$$J_3 = Q_3 \mu_3 \mathcal{E}_3 = Q_3 \mu_3 \left. \frac{dV}{dy} \right|_3$$

$$J_4 = Q_4 \mu_4 \mathcal{E}_4 = Q_4 \mu_4 \left. \frac{dV}{dy} \right|_4$$

$$\Rightarrow \sum_{i=1, N} \frac{J_i dy}{\mu(y)} = \sum_{i=1, N} Q_i dV$$



$$v_d = \frac{-\mu \mathcal{E}}{1 + (|\mathcal{E}|/\mathcal{E}_c)}$$

$$\mu = \frac{\mu_0}{1 + \left(\frac{|\mathcal{E}|}{\mathcal{E}_c}\right)}$$

# Velocity Saturation

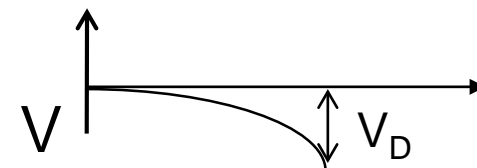
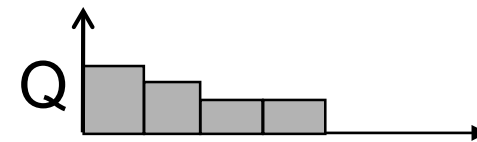
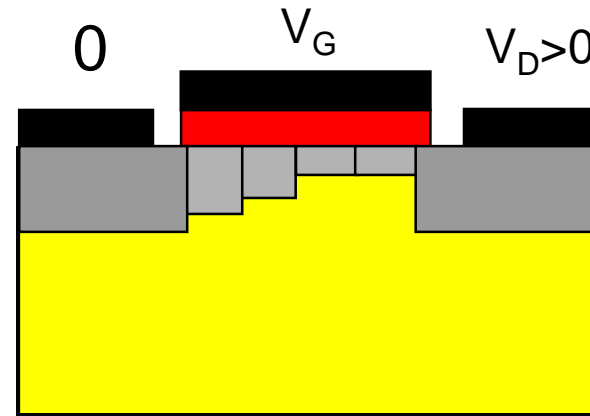
$$\Rightarrow \sum_{i=1,N} \frac{J_i dy}{\mu(y)} = \sum_{i=1,N} Q_i dV$$

$$J_D \sum_{i=1,N} \frac{dy}{\mu_0 / \left[ 1 + \frac{|\mathcal{E}|}{\mathcal{E}_c} \right]} = \int_0^{V_D} C_{ox} (V_G - V_{th} - mV) dV$$

$$\frac{J_D}{\mu_0} \int_0^{L_{ch}} dy \left[ 1 + \frac{1}{\mathcal{E}_c} \frac{dV}{dy} \right] = C_{ox} \left[ (V_G - V_{th}) V_D - \frac{mV_D^2}{2} \right]$$

$$\int_0^{L_{ch}} J_D dy + \int_0^{V_{DS}} \frac{J_D}{\mathcal{E}_c} dV = C_{ox} \left[ (V_G - V_{th}) V_D - \frac{mV_D^2}{2} \right]$$

$$J_D = \frac{\mu_0 C_{ox}}{L_{ch} + \frac{V_D}{\mathcal{E}_c}} \left[ (V_G - V_{th}) V_D - \frac{mV_D^2}{2} \right]$$



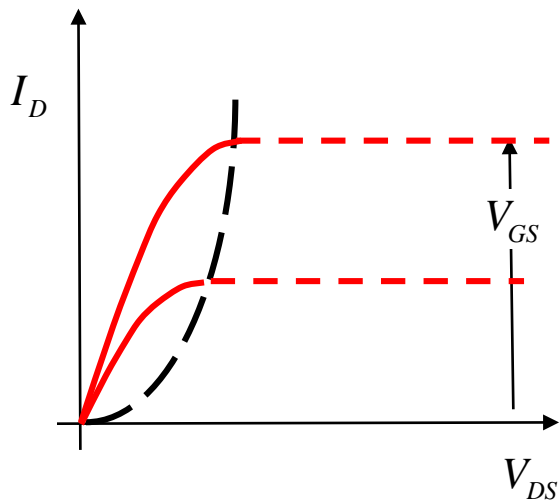
$$v_d = \frac{-\mu \mathcal{E}}{1 + (|\mathcal{E}|/\mathcal{E}_c)}$$

$$\mu = \frac{\mu_0}{1 + \left( \frac{|\mathcal{E}|}{\mathcal{E}_c} \right)}$$

# Significance of the new expression

$$J_D = \frac{\mu_0 C_{ox}}{L_{ch} + \frac{V_D}{\mathcal{E}_c}} \left[ (V_G - V_{th}) V_D - \frac{m V_D^2}{2} \right]$$

- At very small channel lengths and high drain biases, the current expression becomes independent of the channel length
- In the linear region in the  $I$ - $V_D$  characteristics, you have a resistance that doesn't depend on the length of the channel

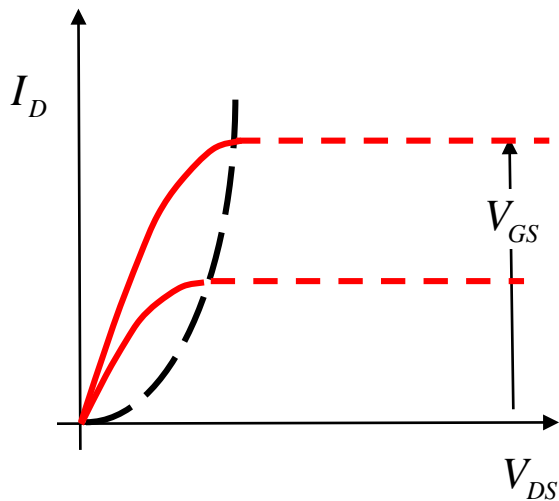


# Calculating $V_{DSAT}$ & $I_{DSAT}$

$$J_D = \frac{\mu_0 C_{ox}}{L_{ch} + \frac{V_D}{\epsilon_c}} \left[ (V_G - V_{th}) V_D - \frac{m V_D^2}{2} \right]$$

$$\frac{dJ_D}{dV_{DS}} = 0$$

Take log on both sides and then set the derivative to zero ....



$$V_{DSAT} = \frac{2(V_G - V_{th}) / m}{1 + \sqrt{1 + 2\mu_o (V_G - V_{th}) / m v_{sat} L_{ch}}} < \frac{(V_{GS} - V_T)}{m}$$

$$J_{D,sat} = \frac{\mu_0 C_{ox}}{L_{ch} + \frac{V_{D,sat}}{\epsilon_c}} \left[ (V_G - V_{th}) V_{D,sat} - \frac{m V_{D,sat}^2}{2} \right]$$

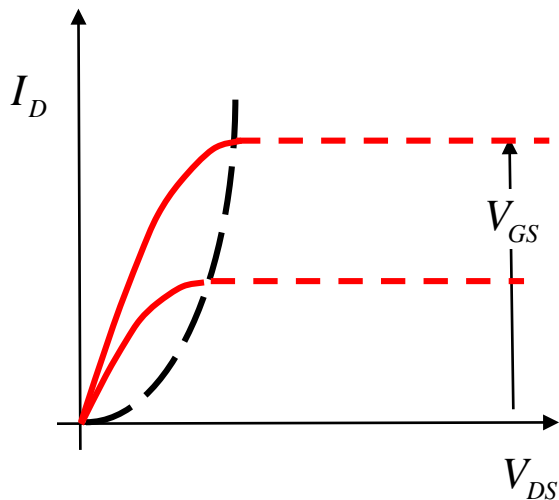
# 'Linear Law' Expression at the limit of $L \rightarrow 0$

$$V_{DSAT} = \frac{2(V_G - V_{th}) / m}{1 + \sqrt{1 + 2\mu_0(V_G - V_{th}) / m v_{sat} L_{ch}}}$$

$$V_{DSAT} \rightarrow \sqrt{2v_{sat} L_{ch} (V_G - V_{th}) / m \mu_0}$$

$$I_{DSAT} = W C_{ox} v_{sat} (V_G - V_{th}) \frac{\sqrt{1 + 2\mu_0(V_G - V_{th}) / m v_{sat} L_{ch}} - 1}{\sqrt{1 + 2\mu_0(V_G - V_{th}) / m v_{sat} L_{ch}} + 1}$$

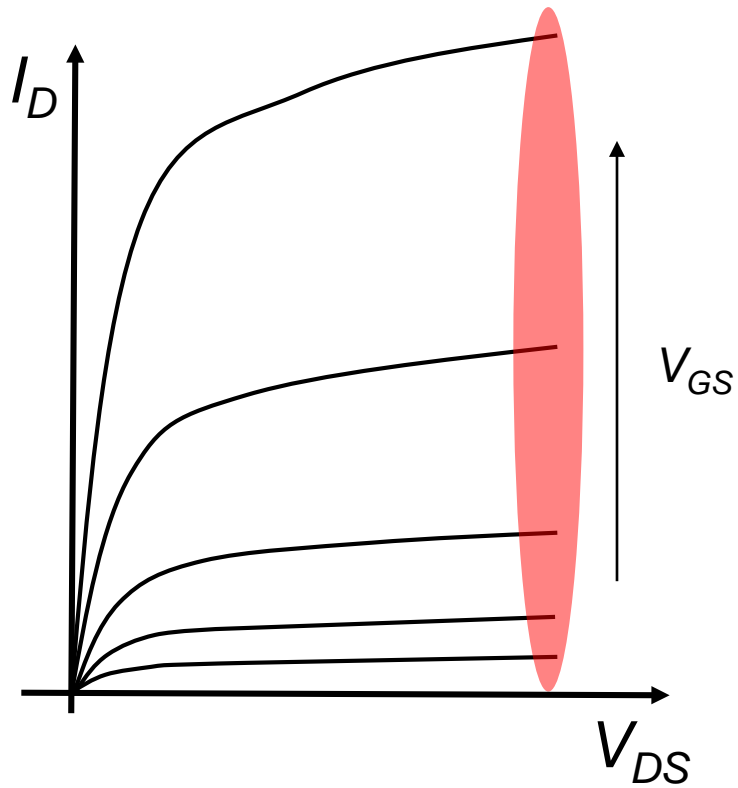
$$I_{DSAT} = W C_{ox} v_{sat} (V_G - V_{th})$$



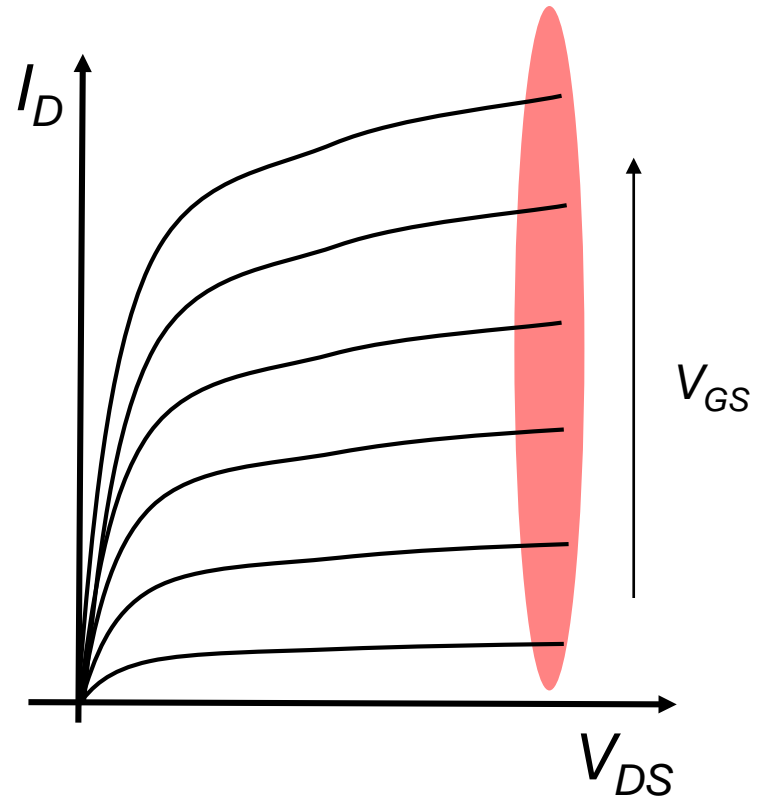
**Complete velocity saturation**  
**Current independent of  $L$**



# 'Signature' of Velocity Saturation



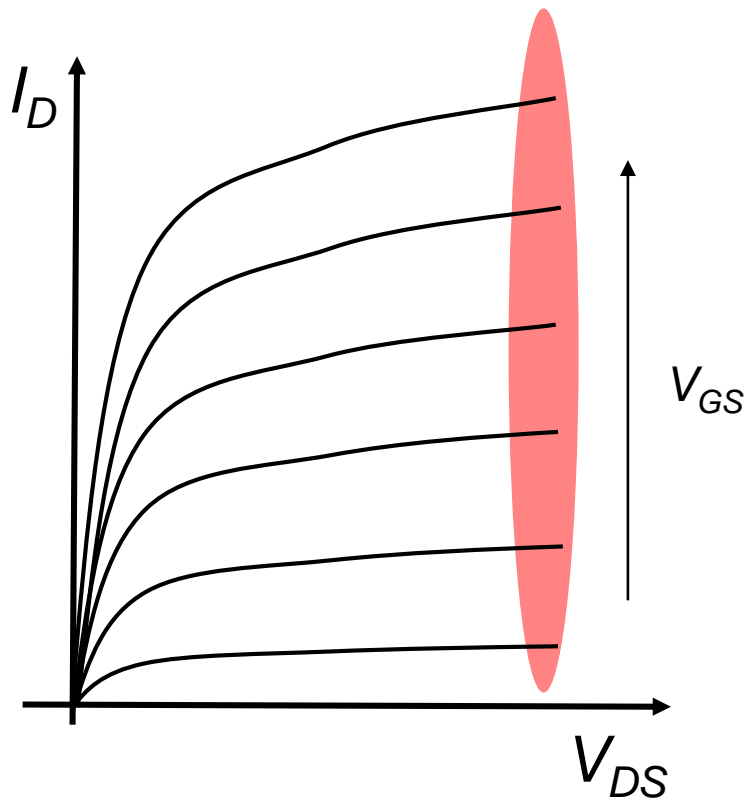
$$I_D = \frac{W}{2L_{ch}} \mu_0 C_{ox} \frac{(V_G - V_{th})^2}{m}$$



$$I_D = W v_{sat} C_{ox} (V_G - V_{th})$$

Can pull out oxide thickness from experimental curves... How?

# $I_D$ and $(V_{GS} - V_T)$ : In practice .....



$$I_D(V_D = V_{DD}) \sim (V_G - V_{th})^\alpha$$

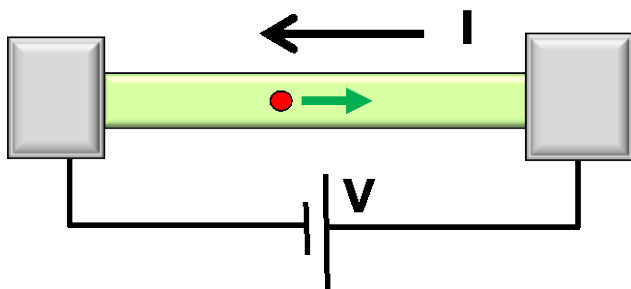
$$1 < \alpha < 2$$

Complete  
velocity  
saturation

Long channel

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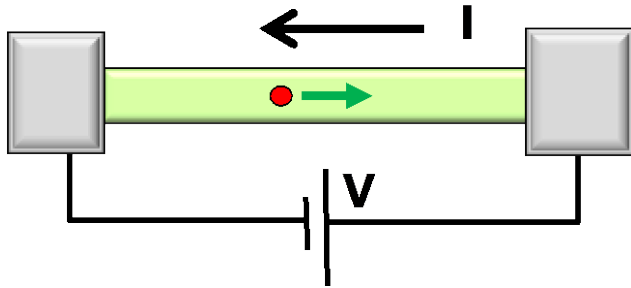
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