

## HW #4 Solution

### Problem 1

To show  $v_1, v_2$  are eigenvectors of  $[A]$  we need to show

$$[A]v_1 = \lambda_1 v_1, \quad [A]v_2 = \lambda_2 v_2.$$

$$\begin{aligned} [A]v_1 &= \begin{bmatrix} \cos \theta & \sin \theta e^{-i\varphi} \\ \sin \theta e^{+i\varphi} & -\cos \theta \end{bmatrix} \begin{Bmatrix} \cos(\frac{\theta}{2}) e^{-i\varphi/2} \\ \sin(\frac{\theta}{2}) e^{+i\varphi/2} \end{Bmatrix} \\ &= \begin{Bmatrix} (\cos \theta \cos(\frac{\theta}{2}) + \sin \theta \sin(\frac{\theta}{2})) e^{-i\varphi/2} \\ (\sin \theta \cos(\frac{\theta}{2}) - \cos \theta \sin(\frac{\theta}{2})) e^{+i\varphi/2} \end{Bmatrix} \\ &= \begin{Bmatrix} \cos(\theta - \frac{\theta}{2}) e^{-i\varphi/2} \\ \sin(\theta - \frac{\theta}{2}) e^{+i\varphi/2} \end{Bmatrix} = 1 \times v_1 \end{aligned}$$

$$\begin{aligned} [A]v_2 &= \begin{bmatrix} \cos \theta & \sin \theta e^{-i\varphi} \\ \sin \theta e^{+i\varphi} & -\cos \theta \end{bmatrix} \begin{Bmatrix} -\sin(\frac{\theta}{2}) e^{-i\varphi/2} \\ \cos(\frac{\theta}{2}) e^{+i\varphi/2} \end{Bmatrix} \\ &= \begin{Bmatrix} -(\cos \theta \sin(\frac{\theta}{2}) - \sin \theta \cos(\frac{\theta}{2})) e^{-i\varphi/2} \\ -(\sin \theta \sin(\frac{\theta}{2}) + \cos \theta \cos(\frac{\theta}{2})) e^{+i\varphi/2} \end{Bmatrix} \\ &= (-1) \times \begin{Bmatrix} -\sin(\theta - \frac{\theta}{2}) e^{-i\varphi/2} \\ \cos(\theta - \frac{\theta}{2}) e^{+i\varphi/2} \end{Bmatrix} = (-1) \times v_2 \end{aligned}$$

$\therefore v_1$  &  $v_2$  are eigenvectors of  $[A]$  and their eigenvalues are 1 & -1 respectively.

Orthogonality

$$V_1^\dagger V_2 = \left\{ \cos\left(\frac{\theta}{2}\right) e^{+i\varphi/2} \quad \sin\left(\frac{\theta}{2}\right) e^{-i\varphi/2} \right\} \begin{Bmatrix} -\sin\left(\frac{\theta}{2}\right) e^{-i\varphi/2} \\ \cos\left(\frac{\theta}{2}\right) e^{+i\varphi/2} \end{Bmatrix}$$

$$= -\cos\left(\frac{\theta}{2}\right) \sin\left(\frac{\theta}{2}\right) + \cos\left(\frac{\theta}{2}\right) \sin\left(\frac{\theta}{2}\right) = 0$$

Problem 2,

We will apply basis transformation such that with this specific basis set,  $[A]$  will be diagonalized.

$$[B] = [V]^\dagger [A] [V]$$

$$= \begin{bmatrix} -v_1^* & \\ & -v_2^* \end{bmatrix} [A] \begin{bmatrix} v_1 & \\ & v_2 \end{bmatrix}$$

$$= \begin{bmatrix} -v_1^* & \\ & -v_2^* \end{bmatrix} \begin{bmatrix} 1 \cdot v_1 & \\ & (-1) \cdot v_2 \end{bmatrix} \quad \left( \begin{array}{l} \text{using } v_1, v_2 \text{ are} \\ \text{eigenvectors} \end{array} \right)$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \quad \left( \text{using orthogonality} \right)$$

Matlab  $\theta = \frac{\pi}{2}, \varphi = 0$   $[A] = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

$$[V, B] = \text{eig}[A]$$

$$V = \begin{bmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad B = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

### Problem 3

As discussed in class or textbook, Hamiltonian is given like this.

$$[H] = \begin{matrix} & \begin{matrix} 1s & 2s & 2p_x & 2p_y & 2p_z \end{matrix} & \\ \begin{matrix} E_1 \\ 0 \\ A \\ 0 \\ 0 \end{matrix} & \begin{bmatrix} E_1 & 0 & A & 0 & 0 \\ 0 & E_2 & B & 0 & 0 \\ A & B & E_2 & 0 & 0 \\ 0 & 0 & 0 & E_2 & 0 \\ 0 & 0 & 0 & 0 & E_2 \end{bmatrix} \end{matrix} \quad (2F_x)$$

Non-zero off diagonal terms will be given by the argument of symmetric/anti-symmetric wavefunctions.

Following the given information in the problem, let's ignore 1s.

$$[H] = \begin{matrix} & \begin{matrix} 2s & 2p_x & 2p_y & 2p_z \end{matrix} & \\ \begin{matrix} E_2 \\ B \\ B \\ E_2 \end{matrix} & \begin{bmatrix} E_2 & B & & \\ B & E_2 & & \\ & & E_2 & \\ & & & E_2 \end{bmatrix} \end{matrix} \quad \text{Block diagonal!}$$

By inspection, eigenvectors & eigenvalues are give like these.

$$\begin{matrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} \\ \downarrow \\ E_2 + B \end{matrix} \quad \begin{matrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} \\ \downarrow \\ E_2 - B \end{matrix} \quad \begin{matrix} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \\ \downarrow \\ E_2 \end{matrix} \quad \begin{matrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \\ \downarrow \\ E_2 \end{matrix}$$

## Problem 4

Energy of system

$$E_{00} = 0, \quad E_{10} = \epsilon_1, \quad E_{01} = \epsilon_2, \quad E_{11} = \epsilon_1 + \epsilon_2$$

$$N_{00} = 0, \quad N_{10} = 1, \quad N_{01} = 1, \quad N_{11} = 2$$

Using law of equilibrium,

$$P_{00} = \frac{1}{Z} \exp\left(-\frac{0-0}{kT}\right)$$

$$P_{01} = \frac{1}{Z} \exp\left(-\frac{(\epsilon_2 - \mu)}{kT}\right)$$

$$P_{10} = \frac{1}{Z} \exp\left(-\frac{(\epsilon_1 - \mu)}{kT}\right)$$

$$P_{11} = \frac{1}{Z} \exp\left(-\frac{(\epsilon_1 + \epsilon_2 - 2\mu)}{kT}\right)$$

$$f_1 = \frac{1}{1 + \exp\left(\frac{\epsilon_1 - \mu}{kT}\right)}$$

$$f_2 = \frac{1}{1 + \exp\left(\frac{\epsilon_2 - \mu}{kT}\right)}$$

$$P_{00} + P_{10} + P_{01} + P_{11} = 1$$

$$Z = 1 + \exp\left(-\frac{(\epsilon_1 - \mu)}{kT}\right) + \exp\left(-\frac{(\epsilon_2 - \mu)}{kT}\right) + \exp\left(-\frac{(\epsilon_1 + \epsilon_2 - 2\mu)}{kT}\right)$$

$$= \left(1 + \exp\left(-\frac{(\epsilon_1 - \mu)}{kT}\right)\right) \left(1 + \exp\left(-\frac{(\epsilon_2 - \mu)}{kT}\right)\right)$$

$$= \frac{1}{(1-f_1)(1-f_2)}$$

$$\therefore P_{00} = (1-f_1)(1-f_2)$$

$$P_{01} = f_2(1-f_1)$$

$$P_{10} = f_1(1-f_2)$$

$$P_{11} = f_1 f_2$$

# Problem # 5,

$$(U_0 = 0.1)$$

$N_\alpha$	$U_{ee} = \frac{U_0 N(N-1)}{2}$	$E_\alpha$	$E_\alpha - N U_\alpha$
0	0	0	0
1	0	$E = 0$	$E - \mu = -\mu$
2	$U_0 = 0.1$	$2E + U_0 = 0.1$	$2E + U_0 - 2\mu = 0.1 - 2\mu$
3	$3U_0 = 0.3$	$3E + 3U_0 = 0.3$	$3E + 3U_0 - 3\mu = 0.3 - 3\mu$
4	$6U_0 = 0.6$	$4E + 6U_0 = 0.6$	$4E + 6U_0 - 4\mu = 0.6 - 4\mu$

$$P_\alpha = \frac{1}{Z} \exp\left(-\frac{(E_\alpha - N_\alpha \mu)}{kT}\right)$$

Regardless of any finite # of degeneracy, In the zero temperature limit, A system with the smallest  $(E - \mu N)$  will dominate.

(exponential factor dominates)

By comparing  $E_\alpha - N U_\alpha$  for various state (equating them to see when the transition occurs)

