

# Lecture 16

## Analytical descriptions of AM-AFM, theory of phase contrast

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# Eigenmodes



1<sup>st</sup> eigenmode

$$(\beta L)_1 = 1.875, (\beta L)_2 = 4.694, (\beta L)_3 = 7.855 \dots$$

Thus



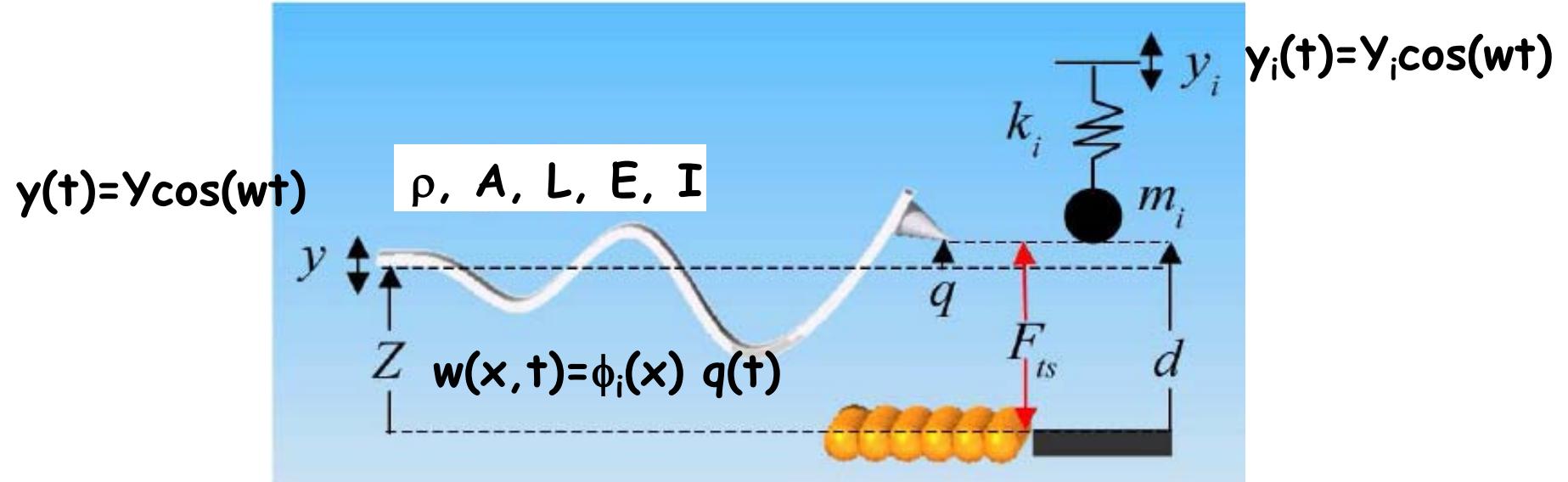
2<sup>nd</sup> eigenmode

for a uniform rectangular lever with negligible tip mass



3<sup>rd</sup> eigenmode

# Equivalent point mass oscillator



## Energy based equivalence principle

$$\frac{1}{2} k_i q^2 = \frac{1}{2} \int_{x=0}^{x=L} EI \left( \frac{d^2 \phi_i}{dx^2} \right)^2 dx \quad \frac{1}{2} m_i q^2 = \frac{1}{2} \int_{x=0}^{x=L} \rho A (\phi_i)^2 dx \quad Y_i = Y \left( \frac{\omega}{\omega_i} \right)^2 \frac{\int_0^L \phi_i(x) dx}{\int_0^L \left( \frac{d^2 \phi_i}{dx^2} \right)^2 dx}$$

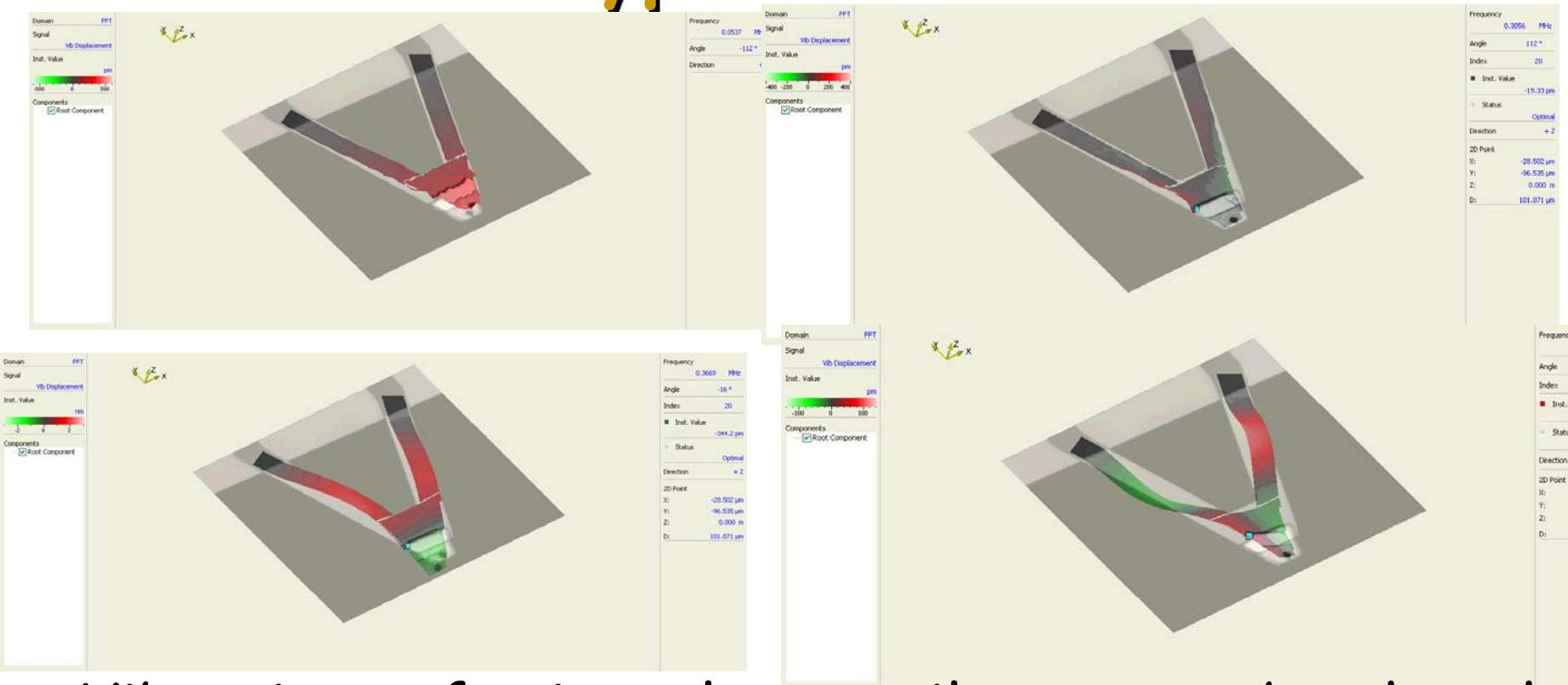
For negligible tip mass

$$k_1 = 1.03k, k_2 = 40.5k, k_3 = 317k$$

$$m_1 = m_2 = m_3 = \dots = 0.249 \rho AL$$

$$Y_1 \sim 1.5Y$$

# Other types of cantilevers

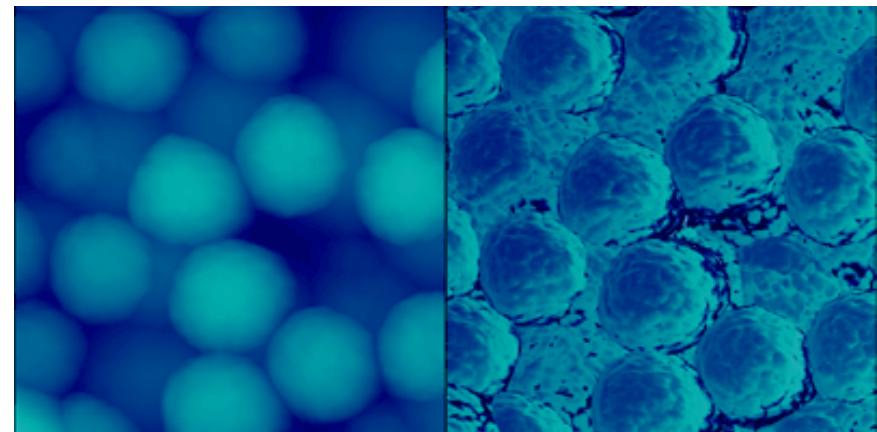
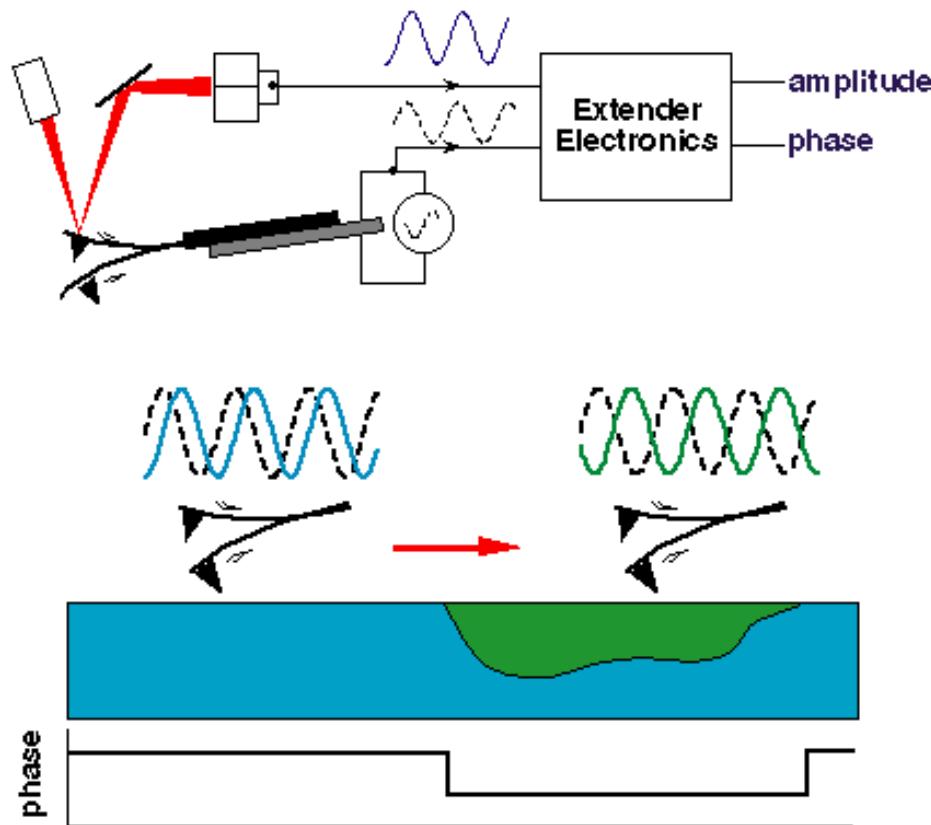


- Vibrations of triangular cantilevers can be thought of as two cantilevers joined together at their tip
- Leads to symmetric and anti-symmetric eigenmodes
- However the point mass oscillator equivalence holds

# Analytical descriptions of AM-AFM

- So far we have resorted to numerical simulations (VEDA) of the point mass model or linearized the equations
- Perturbation methods are quite useful too to help understand
  - Origin of phase contrast
  - Origin of amplitude reduction
  - Average forces while tapping

# Phase Contrast

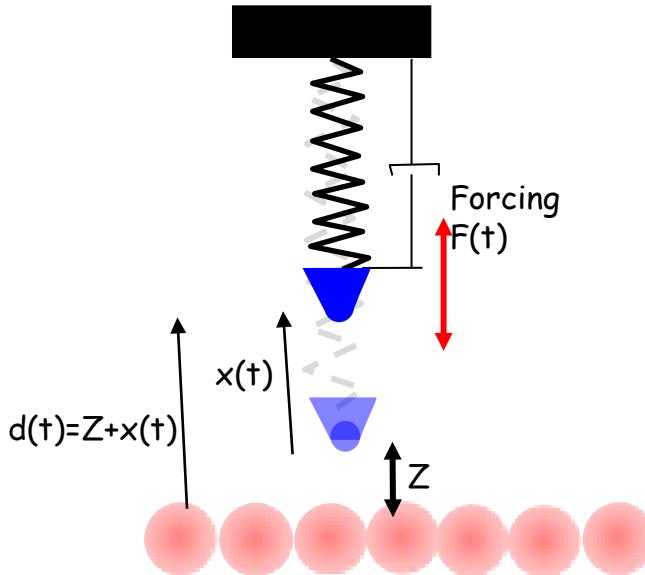


AFM height (left) and phase (right) images  
of poly(methylmethacrylate)

(Veeco, Inc.)

- Regular tapping mode implemented but signal phase monitored
- But what does a phase contrast image mean really?

# Analytical description of AM-AFM



$$m\ddot{x} = -kx - c\dot{x} + F_0 \cos(\omega t) + F_{ts}(d, \dot{d})$$

$$\frac{\ddot{x}}{\omega_0^2} + x + \frac{1}{\omega_0 Q} \dot{x} = \frac{1}{k} (F_0 \cos(\omega t) + F_{ts}(d, \dot{d})) \text{ where} \quad (1)$$

$$\text{with } \omega_0 = \sqrt{\frac{k}{m}}, Q = \frac{m\omega_0}{c}$$

$$\text{Let } x(t) = A \cos(\omega t - \phi) \text{ so that } \dot{x}(t) = \dot{d}(t) = -A\omega \sin(\omega t - \phi) \quad (2)$$

Substitute (2) in (1), we get

$$-\left(\left(\frac{\omega}{\omega_0}\right)^2 - 1\right) \cos(\omega t - \phi) - \left(\frac{\omega}{\omega_0 Q}\right) \sin(\omega t - \phi) = \frac{1}{kA} \{F_0 \cos(\omega t) + F_{ts}(d, \dot{d})\} \quad (3)$$

# Analytical description of AM-AFM

$$x(t) = A \cos(\omega t - \phi) \quad \text{so that} \quad \dot{x}(t) = \dot{d}(t) = -A\omega \sin(\omega t - \phi) \quad (1)$$

$$-\left(\left(\frac{\omega}{\omega_0}\right)^2 - 1\right) \cos(\omega t - \phi) - \left(\frac{\omega}{\omega_0 Q}\right) \sin(\omega t - \phi) = \frac{1}{kA} \left\{ F_0 \cos(\omega t) + F_{ts}(d, \dot{d}) \right\} \quad (2)$$

$$\int_{t=0}^{2\pi/\omega} \sin(\omega t - \phi) \times (\cdot) dt \Rightarrow -\left(\frac{\omega}{\omega_0 Q}\right) \frac{\pi}{\omega} = -\frac{1}{kA} \frac{\pi}{\omega} F_0 \sin(\phi) + \frac{1}{kA} \int_{t=0}^{2\pi/\omega} \sin(\omega t - \phi) \times F_{ts}(d, \dot{d}) dt$$

$$Or, \sin(\phi) = \frac{kA}{F_0} \left\{ \frac{\omega}{Q\omega_0} - \frac{1}{\pi kA^2} \int_{t=0}^{2\pi/\omega} (-A\omega \sin(\omega t - \phi)) \times F_{ts}(d, \dot{d}) dt \right\} = \frac{kA}{F_0} \left\{ \frac{\omega}{Q\omega_0} - \frac{1}{\pi kA^2} E_{diss} \right\} \quad (3)$$

But  $\frac{kA_0}{F_0} = \sqrt{\left(1 - \left(\frac{\omega}{\omega_0}\right)^2\right)^2 + \left(\frac{\omega}{\omega_0 Q}\right)^2}$  so we get

$$\sin(\phi) = \frac{1}{\sqrt{\left(1 - \left(\frac{\omega}{\omega_0}\right)^2\right)^2 + \left(\frac{\omega}{\omega_0 Q}\right)^2}} \left\{ \frac{\omega}{Q\omega_0} \frac{A}{A_0} - \frac{1}{\pi kAA_0} E_{diss} \right\} \quad (4)$$

$$If \omega = \omega_0 \text{ then } \sin(\phi) = \left\{ \frac{A}{A_0} - \frac{Q}{\pi kAA_0} E_{diss} \right\}$$

■  $A/A_0 = \text{constant in tapping mode scan}$

■ Phase contrast = energy dissipation contrast!

# Analytical description of AM-AFM

- Conversely

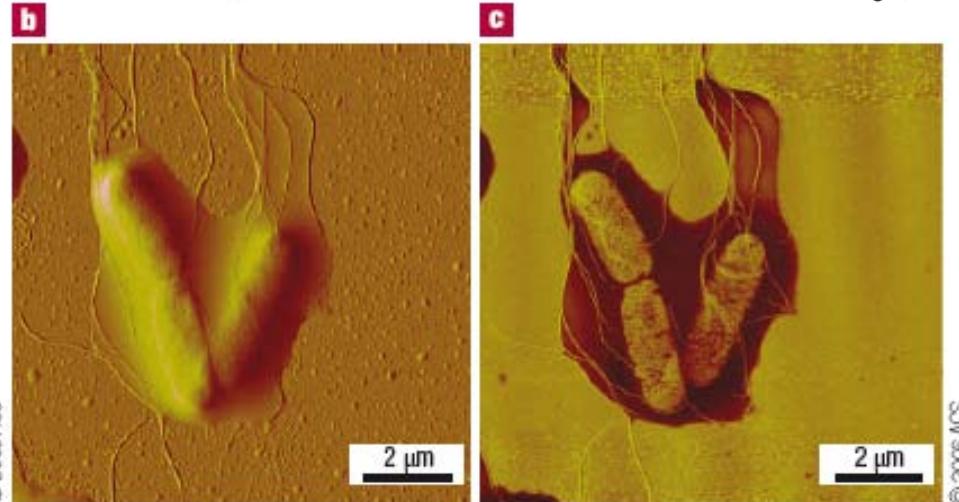
$$E_{diss} = \pi k A A_0 \left\{ \frac{\omega}{Q \omega_0} \frac{A}{A_0} - \sin(\phi) \sqrt{\left(1 - \left(\frac{\omega}{\omega_0}\right)^2\right)^2 + \left(\frac{\omega}{\omega_0 Q}\right)^2} \right\} \quad (1)$$

If  $\omega = \omega_0$

$$E_{diss} = \frac{\pi k}{Q} \{ A^2 - A_0 A \sin(\phi) \} \quad (2)$$

- Eq. (7) relates the energy dissipated per cycle due to tip-sample interaction to observables
- By quantitative knowledge of  $Q$ ,  $k$ ,  $A$ ,  $A_0$ , and  $f$  it becomes possible to know in an experiment the energy dissipated in eV or pJ per cycle

# Phase contrast imaging in air/vacuum



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(φ). b,c, The above considerations are illustrated by comparing the topography of an aggregate of three *Salmonella typhimurium* cells covered by an extracellular polymeric capsule (b) and the phase image (c), that is acquired simultaneously with the topography, reveals the inner structure of the cell as well as the continuity of flagellae. (R. Avci et al. ref. 49 © 2007 American Chemical Society).

■ From Garcia et al  
*Nature Materials*, 6, 2007



**Figure 4** Complex microdomain structure of a block copolymer. The AFM images are rendered into three-dimensions using the height image as height-field and the phase image as contrast. The images show the formation of terraces in a thin film of SBS block copolymer and the systematic change of microdomain structures along the changes in film thickness from 32 nm at the lowest terrace to 57 nm at the higher terrace. Reprinted with permission from ref. 54.

# Origin of amplitude reduction

$$x(t) = A \cos(\omega t - \phi) \text{ so that } d(t) = Z + A \cos(\omega t - \phi) \text{ and } \dot{x}(t) = \dot{d}(t) = -A\omega \sin(\omega t - \phi) \quad (1)$$

$$-\left(\left(\frac{\omega}{\omega_0}\right)^2 - 1\right) \cos(\omega t - \phi) - \left(\frac{\omega}{\omega_0 Q}\right) \sin(\omega t - \phi) = \frac{1}{kA} \left\{ F_0 \cos(\omega t) + F_{ts}(d, \dot{d}) \right\} \quad (2)$$

$$\int_{t=0}^{2\pi/\omega} \sin(\omega t - \phi) \times (\bullet) dt \Rightarrow$$

$$\frac{1}{kA} F_0 \sin(\phi) = \left( \frac{\omega}{\omega_0 Q} \right) + \frac{\omega}{\pi kA} \int_{t=0}^{2\pi/\omega} \sin(\omega t - \phi) \times F_{ts}(d, \dot{d}) dt = \left( \frac{\omega}{\omega_0 Q_{eff}} \right) \quad (3)$$

$$\text{with } \frac{1}{Q_{eff}} = \frac{1}{Q} + \frac{\omega_0}{\pi kA} \int_{t=0}^{2\pi/\omega} \sin(\omega t - \phi) \times F_{ts}(d, \dot{d}) dt$$

$$\int_{t=0}^{2\pi/\omega} \cos(\omega t - \phi) \times (\bullet) dt \Rightarrow$$

■ L. Wang et al App. Phys. Lett., 73, 3781, 1998

$$\frac{F_0 \cos(\phi)}{kA} = \omega_{eff}^2 - \left( \frac{\omega}{\omega_0} \right)^2 \quad (4)$$

$$\text{with } \omega_{eff}^2 = 1 - \frac{\omega}{\pi kA} \int_{t=0}^{2\pi/\omega} \cos(\omega t - \phi) \times F_{ts}(d, \dot{d}) dt$$

Combining (1) (2)

$$A = \frac{F_0 / k}{\sqrt{\left( \left( \frac{\omega}{\omega_0} \right)^2 - \omega_{eff}^2 \right)^2 + \left( \frac{\omega}{\omega_0 Q_{eff}} \right)^2}} \quad (5)$$

# Origin of amplitude reduction

$x(t) = A \cos(\omega t - \phi)$  so that  $d(t) = Z + A \cos(\omega t - \phi)$  and  $\dot{x}(t) = \dot{d}(t) = -A\omega \sin(\omega t - \phi)$  (1)

$$A = \frac{F_0 / k}{\sqrt{\left(\left(\frac{\omega}{\omega_0}\right)^2 - \omega_{eff}^2\right)^2 + \left(\frac{\omega}{\omega_0 Q_{eff}}\right)^2}}$$

$$\text{with } \frac{1}{Q_{eff}} = \frac{1}{Q} + \frac{\omega_0}{\pi k A} \int_{t=0}^{2\pi/\omega} \sin(\omega t - \phi) \times F_{ts}(d, \dot{d}) dt = \frac{1}{Q} - \frac{\omega_0}{\omega \pi k A^2} E_{diss}$$

$$\text{and } \omega_{eff}^2 = 1 - \frac{\omega}{\pi k A} \int_{t=0}^{2\pi/\omega} \cos(\omega t - \phi) \times F_{ts}(d, \dot{d}) d t$$

- At high Q, amplitude decreases due to shift in nonlinear effective frequency

# Average force

$$\frac{F_0 \cos(\phi)}{kA} = \omega_{eff}^2 - \left( \frac{\omega}{\omega_0} \right)^2 \quad (1)$$

with  $\omega_{eff}^2 = 1 - \frac{\omega}{\pi kA} \int_{t=0}^{2\pi/\omega} \cos(\omega t - \phi) \times F_{ts}(d, \dot{d}) dt$

Consider conservative forces only  $F_{ts}(d)$

$$\begin{aligned} \omega_{eff}^2 &= 1 - \frac{\omega}{\pi kA} \int_{t=0}^{2\pi/\omega} \cos(\omega t - \phi) \times F_{ts}(d) dt = 1 - \frac{\omega}{\pi kA^2} \int_{t=0}^{2\pi/\omega} A \cos(\omega t - \phi) \times F_{ts}(Z + A \cos(\omega t - \phi)) dt \\ &\sim 1 + \frac{\omega}{\pi kA} \frac{2\pi}{\omega} \langle F_{ts}(d) \rangle = 1 + \frac{2}{kA} \langle F_{ts}(d) \rangle \quad (2) \end{aligned}$$

Valid when contact time  $\ll$  oscillation period

$$\frac{2}{kA} \langle F_{ts}(d) \rangle = \frac{F_0 \cos(\phi)}{kA} - 1 + \left( \frac{\omega}{\omega_0} \right)^2 \quad (3)$$

*San Paulo and Garcia PRB, 64, 2001*

When  $\omega = \omega_0$

$$\langle F_{ts}(d) \rangle = \frac{F_0 \cos(\phi)}{2} = \frac{F_0}{2} \sqrt{1 - \sin^2 \phi} = \frac{F_0}{2} \sqrt{1 - \left( \frac{A}{A_0} \right)^2} = \frac{kA}{2Q} \sqrt{1 - \left( \frac{A}{A_0} \right)^2} \quad (4)$$

- Depends only on cantilever properties and operating conditions !!

# Analytical description of AM-AFM

$$x(t) = A \cos(\omega t - \phi) \quad \text{so that} \quad \dot{x}(t) = \dot{d}(t) = -A\omega \sin(\omega t - \phi) \quad (1)$$

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# Average force

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with  $\omega_{eff}^2 = 1 - \frac{\omega}{\pi kA} \int_{t=0}^{2\pi/\omega} \cos(\omega t - \phi) \times F_{ts}(d, \dot{d}) dt$

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# Next time

- Peak forces
- Stiffness calibration methods