Experimental uncertainties in extracting material properties from F-Z curves

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AFM Force Displacement (F-Z) Curve Experiment



AFM F-Z Curve Analysis





- Nomenclature:
 - F Tip-sample force
 - Z_{nm} Z-piezo Displacement
 - d Tip-sample distance

Parameter of Interest

Elastic modulus (E) is estimated by fitting a model for tip-sample interaction to the F-d Curve

F-Z curve calibration

- 3 calibration parameters needed:
 - nm to V conversion for Z-piezo input signal (C_z)
 - nm to V conversion for photodiode output signal (C_L)
 - nm to nN conversion for cantilever deflection (\mathbf{k}_{L})



Z-Piezo calibration

 If we assume a linear relationship between voltage input into the Z-Piezo and displacement output

$$Z_{nm} = C_Z Z_V$$

- One method:
 - Scan a sample of "known" height



Good Assumption?



Photodiode calibration

$$\partial_{nm} = C_L \partial_V = m C_Z \partial_V$$

- One method:
 - Assume that the cantilever and Z-piezo move with a one to one ratio when the sample is "stiff"

Cantilever Stiffness calibration

- Large body of literature regarding stiffness calibration (> 100 papers).
- A few common methods include:
 - Sader's method, Thermal Methods, and Cleveland's Method

Calibration "Paths"

• Recap:

- Measure a sample of known height.

 $C_{Z} = f(\partial_{V}, Z_{V})$

– Measure a F-Z curve on a stiff sample.

 $C_L = f(\partial_V, Z_V, C_Z)$

– Measure the thermal oscillations of the cantilever:

 $k_L \!=\! f(\partial_V,\! C_L,\! T)$

• This is not the only method.

Cantilever tilt correction

Hutter, Comment on Tilt of Atomic Force Microscope Cantilevers: Effect on Spring Constant and Adhesion Measurements, Langmuir V 21, 2005

Force-Distance (F-d) Curves

 Need to convert F-Z curve into F-d curve because the tip sample interaction models are given in terms of F versus d

$$d = Z_{nm} - \partial_{nm}$$
$$= C_Z Z_V - C_L \partial_V$$
$$= C_Z (Z_V - m \partial_V)$$

Tip-Sample interaction models

• Many ways to model the interaction of the AFM tip with the sample.

F = f(d, material properites, surface geometry)

 One example is the Derjaguin Muller Toporov (DMT) model

DMT contact mechanics

• Modification of Hertz model to include adhesive forces:

$$F = S(d - a_0)^{3/2} - F_0$$

$$f$$
Intermolecular distance

Constant related in tip and sample properties and geometry

• F₀ is related to work of adhesion between tip and sample as:

$$F_0 = 4\pi \frac{W}{\hat{R}}$$

Effect of surface geometry on DMT model

Effect of surface geometry on DMT model

• For the geometry of a sphere interacting with a cylinder S can be related to E via the equations*:

$$S = \frac{2\pi (\tilde{E}(k_p))^{1/2}}{3\sqrt{1-k_p^2} (\tilde{K}(k_p))^{3/2} (\hat{R})^{1/2} \hat{E}}$$

$$\begin{split} \widetilde{K}(k_{p}) &\equiv \int_{0}^{\pi/2} \frac{d\theta}{\sqrt{1 - k_{p}^{2} \sin^{2}(\theta)}} \quad \widetilde{E}(k_{p}) &\equiv \int_{0}^{\pi/2} \sqrt{1 - k_{p}^{2} \sin^{2}(\theta)} d\theta \quad \widehat{R} &\equiv \frac{1}{2} \left(\frac{1}{R_{1}} + \frac{1}{R_{2}} + \frac{1}{R_{1}^{'}} + \frac{1}{R_{2}^{'}} \right) \\ \widehat{E} &= \left(\frac{1 - v^{2}}{E} + \frac{1 - v_{ip}^{2}}{E_{iip}} \right) \end{split}$$

 k_p is found by solving

$$\left(\frac{\frac{1}{R_1} + \frac{1}{R_2}}{\frac{1}{R_1} + \frac{1}{R_2}}\right) = \frac{1/(1 - k_p^2) * \widetilde{E}(k_p) - \widetilde{K}(k_p)}{\widetilde{K}(k_p) - \widetilde{E}(k_p)}$$

• E is directly proportional to S if E >> E_{tip}

*Boresi, A.P. 1978 Advanced Mechanics of Materials 3th Edition. New York: Wiley.

Effect of surface geometry on DMT model

- Common geometry in AFM
 - Sphere-Sphere:

$$S = \frac{4}{3} \frac{1}{\hat{E}} \left(\frac{1}{R_{tip}} + \frac{1}{R_{surf}} \right)^{-1/2}$$

- Sphere-Plane:

$$S = \frac{4\sqrt{R_{tip}}}{3\hat{E}}$$

Curve fitting procedure for DMT model

• The DMT model can be linearized by defining a parameter d* such that:

 $d^* = (d - a_0)^{3/2}$

The linearized model is then given as:

$$F = Sd * - F_0$$

• S and F_0 can then be found from the n data pairs (F_i , d_i^*) as:

$$S = \frac{n \sum_{i=1}^{n} d_{i}^{*} F_{i} - \sum_{i=1}^{n} d_{i}^{*} \sum_{i=1}^{n} F_{i}}{n \sum_{i=1}^{n} (d_{i}^{*})^{2} - \left(\sum_{i=1}^{n} d_{i}^{*}\right)^{2}}$$

$$F_{0} = \frac{\sum_{i=1}^{n} (d_{i}^{*})^{2} \sum_{i=1}^{n} F_{i} - \sum_{i=1}^{n} d_{i}^{*} \sum_{i=1}^{n} d_{i}^{*} F_{i}}{n \sum_{i=1}^{n} (d_{i}^{*})^{2} - \left(\sum_{i=1}^{n} d_{i}^{*}\right)^{2}}$$

$$R_{gof}^{2} = \frac{\sum_{i=1}^{n} (F_{i} - F_{i}^{*})^{2}}{\sum_{i=1}^{n} (F_{i} - F_{i})^{2}}$$

 One additional complications arises as Z_V is a relative measurement hence the d value resulting from this procedure can be offset by a constant value. This Constant is found by maximizing the R²_{gof} value of the curve fit.

Summary

 We can consider the above process as inputting 2n+11 or 2n+8 (n is number of data points in F-Z curve) parameters into a "Data Reduction Equation" and outputting elastic modulus or work of adhesion

 $E = f_1(Z_{V_1}^*, ..., Z_{V_n}^*, \delta_{V_1}^*, ..., \delta_{V_n}^*, Z_{V, shift}, \delta_{V, shift}, C_Z, m, k_L, \alpha, R_V, R_{tip}, E_{tip}, \nu_{tip}, \nu)$

 $W = f_2(Z_{V_1}^*, ..., Z_{V_n}^*, \delta_{V_1}^*, ..., \delta_{V_n}^*, Z_{V, shift}, \delta_{V, shift}, C_Z, m, k_L, \alpha, R_V, R_{tip})$

Case study: Cellulose Nanocrystals

Uncertainty in measurement

- Lab A and B are given a sample, say X.
 - Lab A \rightarrow flux capacitance = 7
 - Lab B \rightarrow flux capacitance = 30
 - Are these measurements in agreement?

Classifications of uncertainty

- 3 classification systems
 - Random and systematic
 - Random Varies over the course of the experiment
 - Systematic Does not vary over the course of the experiment
 - Aleatory and Epistemic
 - Aleatory Uncertainty associated with parameters within a model
 - Epistemic Uncertainty associated with the form of the model
 - Type A and type B
 - Type A Evaluated by statistical means
 - Type B Evaluated by other means

Uncertainty Propagation

Let r be a measured variable then

 \mathbf{b}_{r} – systematic standard uncertainty associated with r \mathbf{s}_{r} –random standard uncertainty associated with r \mathbf{u}_{r} – standard combined uncertainty associated with r

 $u_r = (s_r^2 + \sum b_r^2)^{1/2}$

 $U_{x,r}$ – expanded uncertainty estimate associated with r:

$$U_{x,r} = k_x u_r$$

 ${\bf U_{x,\,r}}$ corresponds to the range that we are x percent confident that the true value of r falls within r_{best} \pm $U_{x,\,r}$

If we have $f(r_1, ..., r_n)$ the then uncertainty in f propagates as:

$$u_f = \left(\sum_{i=1}^n \left(\frac{df}{dr_i}u_{r_i}\right)^2\right)^{1/2}$$

Taylor Series uncertainty propagation formula

Uncertainty Propagation

Summary

 Applying the Taylor series uncertainty propagation formula to the data reduction equations results in:

$$\begin{aligned} u_E &= ((\frac{df_1}{dZ_{V_1}}u_{V_1})^2 + \ldots + (\frac{df_1}{dZ_{V_n}}u_{Z_{V_n}})^2 + (\frac{df_1}{d\delta_{V_1}}u_{\delta_{V_1}})^2 + \ldots + (\frac{df_1}{d\delta_{V_n}}u_{\delta_{V_n}})^2 + \\ &\quad (\frac{df_1}{dZ_{V,shift}}u_{Z_{V,shift}})^2 + (\frac{df_1}{d\delta_{V,shift}}u_{\delta_{V,shift}})^2 + (\frac{df_1}{dC_Z}u_{C_Z})^2 + (\frac{df_1}{dm}u_m)^2 + \\ &\quad (\frac{df_1}{dk_L}u_{k_L})^2 + (\frac{df_1}{d\alpha}u_\alpha)^2 + (\frac{df_1}{dR_V}u_{R_V})^2 + (\frac{df_1}{dR_{tip}}u_{R_{tip}})^2 \\ &\quad + (\frac{df_1}{dE_{tip}}u_{E_{tip}})^2 + (\frac{df_1}{d\nu_{tip}}u_{\nu_{tip}})^2 + (\frac{df_1}{d\nu}u_\nu)^2)^{1/2} \end{aligned}$$

(Result for W is similar)

Case Study Cellulose Nanocrystals

Case Study: Cellulose Nanocrystals¹

1. Wagner R., Raman A., Moon. R. "Uncertainty quantification in nanomechanical measurements using the Atomic Force Microscope" In Preparation 2010.

Sensitivity Analysis

Sample Uncertainty Table for Elastic Modulus Analysis							
Variable (x)	Description	Value	Standard Uncertainty (u _x)	Sensitivity (dE/dx)	Contribution to Elastic Modulus Variance (dE/dx u _x) ²		
Calibration	n Parameters:						
Cz	Z-piezo Sensitivity	14 (nm/V)	1 (nm/V)	0.5 (GPa V/nm)	0.03 (GPa ²)		
m	Nondimentional Photodiode Sensitivity	6.1 ()	0.15 ()	25 (GPa)		14 (GPa²)	>
α	Tilt Correction Factor	1.037 ()	0.007 ()	10 (GPa)		0.01 (GPa ²)	
κ _L	Cantilever Stiffness	2.5 (nN/nm)	0.1 <mark>(</mark> nN/nm)	5 (GPa nm/nN)	0.02 (GPa ²)		
δ _{V, Shift}	Photodiode voltage Shift Factor	-0.36 (V)	0.01 (V)	0.0002 (GPa/ V)		4 E -12 (GPa ²)	
Model Parameters:							
R _{tip}	Radius of AFM tip	10 (nm)	1 (nm)	0.4 (Gpa/nm)	0.16 (GPa ²)		
E _{tip}	Elastic Modulus of AFM tip	100 (GPa)	3 (GPa)	0.01 ()	0.001 (GPa ²)		
V _{tip}	Poisson's Ratio of AFM tip	0.28 ()	0.02 ()	0.6 (GPa)	0.001 (GPa ²)		
R _v	Radius of Sample measured with AFM	0.31 (V)	.04 (V)	6 (GPa/V)	0.05 (GPa ²)		
v	Poisson's Ratio of Sample	0.28 ()	0.05 ()	6 (GPa)	0.01 (GPa ²)		
Data pairs sampled during experiment :			Mean Sensitivity	Mean Variance Contribution	Total Variance Contribution		
Z _{vi}	Z-piezo voltage	(V)	0.0002 (V)	30 (GPa/V)	0.00004 (GPa ²)	0.004 (GPa ²)	
δ _{Vi}	Photodiode voltage	(V)	0.0002 (V)	170 (GPa/V)	0.001 (GPa ²)	0.2 (GPa ²)	
Totai:				Expanded Uncertainty (k _p = 2)	Variance		
E	Elastic Modulus	10 .3 (Gpa)	3.8 (GPa)	7.6 (GPa)		15 (GPa ²)	>